

Using ROS Node

This command allows the user to gather information about any running node.

Getting Node Info

```
roscall info <NODE>
```

Pinging a Node

```
roscall ping <NODE>
```

Listing Running Nodes

```
roscall list
```

Get a List of All Machines on the Network

```
roscall machine
```

Get a List of Nodes Running on a Machine

```
roscall machine <MACHINE_NAME>
```

Kill a Running Node

```
roscall kill <NODE>
```

Clean the Server of Unresponsive Nodes

```
roscall cleanup
```

From:
<http://robosub-vm.eecs.wsu.edu/wiki/> - Palouse RoboSub Technical Documentation

Permanent link:
<http://robosub-vm.eecs.wsu.edu/wiki/cs/ros/rosnode/start>

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