

ROS

We use ROS as our communication framework to allow different processes to talk with each other.

Learning ROS

The [official ROS tutorials](#) are very comprehensive, however I found the way they present ROS to a beginner results in a very steep learning curve. [Here is our own set of tutorials](#), which are a work in progress.

Issues

Check out this page for common errors and fixes: [common errors and fixes](#)

From:

<http://robosub-old.eecs.wsu.edu/wiki/> - **Palouse RoboSub Technical Documentation**

Permanent link:

<http://robosub-old.eecs.wsu.edu/wiki/cs/ros/start>

Last update: **2016/09/23 21:32**

