

# ROS

We use ROS as our IPC framework.

- [Installation Instructions](#)
- [common errors and fixes](#)

From:

<http://robosub-old.eecs.wsu.edu/wiki/> - **Palouse RoboSub Technical Documentation**

Permanent link:

<http://robosub-old.eecs.wsu.edu/wiki/cs/ros/start?rev=1472792990>



Last update: **2016/09/01 22:09**