

ROS

We use ROS as our communication framework to allow different processes to talk with each other.

Learning ROS

The [official ROS tutorials](#) are very comprehensive, however I found the way they present ROS to a beginner to be a very steep learning curve. Here is our own set of tutorials, which are a work in progress.

Issues

Check out this page for common errors and fixes: [common errors and fixes](#)

From:

<http://robosub-old.eecs.wsu.edu/wiki/> - **Palouse RoboSub Technical Documentation**

Permanent link:

<http://robosub-old.eecs.wsu.edu/wiki/cs/ros/start?rev=1473467160>



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