

# Running Gazebo Simulator

Next build everything by running `catkin_make`. Then run the following command:

```
roslaunch robosub_simulator gazebo.launch
```

From:

<http://robosub-old.eecs.wsu.edu/wiki/> - **Palouse RoboSub Technical Documentation**

Permanent link:

<http://robosub-old.eecs.wsu.edu/wiki/cs/simulator/run/start?rev=1481585083>



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