Running Gazebo Simulator

Next build everything by running catkin_make. Then run the following command:

```
roslaunch robosub_simulator gazebo.launch
```

this will load the proper param files, start up gazebo with the correct world, spawn the sub, and finally, start the simulator bridge.

From:
http://robosub-old.eecs.wsu.edu/wiki/ - **Palouse RoboSub Technical Documentation**

Permanent link:
http://robosub-old.eecs.wsu.edu/wiki/cs/simulator/run/start?rev=1481585596

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