

Simulator

The current simulator uses Gazebo and is integrated with ROS. For information about running the simulator [look here](#).

From:

<http://robosub-vm.eecs.wsu.edu/wiki/> - **Palouse RoboSub Technical Documentation**

Permanent link:

<http://robosub-vm.eecs.wsu.edu/wiki/cs/simulator/start>



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